

## Simple Harmonic Motion (SHM)

$$\ddot{x} = -\omega^2 x, \quad x = A \cos(\omega t + \phi), \quad \omega = 2\pi f = 2\pi/T$$

- $\omega = \sqrt{k/m}$  (mass on spring, horizontal or vertical;  $F_{net} = -kx$ ; the gravity effectively disappears from the problem in the vertical spring problem if  $x$  measures the displacement relative to the new equilibrium *with* mass on spring).
- $\omega = \sqrt{\kappa/I}$  (rotation; pendulum or torsion oscillator; torque  $\tau_{net} = -\kappa\theta = I\ddot{\theta}$ ,  $|\theta| \ll 1$ ).
- $\omega = \sqrt{mgl/I}$  (any physical pendulum;  $\kappa = mgl$ ,  $l$  = distance from pivot to the center of mass),  $\omega = \sqrt{g/l}$  (simple pendulum;  $I = ml^2$ ).
- For pendulum or torsion oscillator,  $\theta = \theta_{max} \cos(\omega t + \phi)$ , and  $\omega \neq \dot{\theta}$ .

### Other kinematic quantities

$$\dot{x} = -\omega A \sin(\omega t + \phi) \quad \text{velocity; max speed} = A\omega$$

$$\ddot{x} = -\omega^2 x = -A\omega^2 \cos(\omega t + \phi) \quad \text{acceleration; max acceleration} = A\omega^2$$

### Energy conservation

$$E = K(t) + U(t) = U_{max} = K_{max} = \frac{1}{2}m\omega^2 A^2 \text{ or } \frac{1}{2}I\omega^2 \theta_{max}^2 = \text{constant in time}$$

$$U(t) = \frac{1}{2}m\omega^2 x^2 \text{ or } \frac{1}{2}I\omega^2 \theta^2, \quad K(t) = \frac{1}{2}m\dot{x}^2 \text{ or } \frac{1}{2}I\dot{\theta}^2$$

## Wave

Any wave can be broken down into travelling sinusoidal waves (Fourier series/integral). A **travelling sinusoidal wave** (a “**plane wave**”) and a standing sinusoidal wave are of our utmost concern. A **spherical wave** or a circular wave is also of our concern, and is a more realistic wave from a small source in three or two dimensions. However, locally, they can be approximated as plane waves.

$$D_{\pm}(x, t) = A \sin(kx \pm \omega t + \phi) \quad \text{travelling sinusoidal wave}$$

$$D_s(x, t) = D_+ + D_- = 2A \sin(kx + \phi) \cos(\omega t) \quad \text{standing sinusoidal wave}$$

The travelling sinusoidal wave has a sine shape and it is moving at the **wave speed**  $v = \omega/k$  (this formula valid **only for** travelling sinusoidal wave) right (-) or left (+). The standing sinusoidal wave has a sine shape which is not moving, but experiencing a “time dependent amplitude/ scaling-factor”  $2A \cos(\omega t)$ : so it is “breathing,” rather than moving. So, the wave speed for a standing wave is zero. In either case,

$$\lambda = \frac{2\pi}{k}. \quad \text{wave length } (\lambda), \text{ wave number } (k; \text{ not } k \text{ in Hooke's law force } -kx!)$$

A **transverse wave** (e.g., a string wave) is a wave for which  $D$  and the wave velocity (or  $k$  = wave number, or wave *vector*) are perpendicular to each other, and a **longitudinal wave** (e.g., a sound wave in air/water) is a wave for which  $D$  and the wave velocity (or  $k$  = wave number, or wave *vector*) are along the same axis.

For the above sinusoidal waves (travelling or standing), the local motion, for fixed value of  $x$ , is just a SHM (just examine  $D_{\pm}$  and  $D_s$  as a function of  $t$ )! Physically, this means that a sinusoidal wave is a coordinated SHM, where each *particle* defined by the small segment between  $x$  and  $x + dx$  is going through a SHM and this motion transpires to its neighbors. For this reason,  $\omega$  (or  $f$ ) is a **preserved quantity** when a wave propagates/reflects/refracts/diffracts/etc. in an inhomogeneous medium environment. The **particle velocity** is given by  $\partial D/\partial t$ , and should not be confused with the **wave velocity**. For travelling wave (sinusoidal or not), the **wave speed** is given by  $v = \sqrt{F_T/\mu}$  (string wave), or  $\sqrt{B/\rho}$  (sound wave in gas/liquid), etc.

**Superposition principle** is the fundamental principle of waves. It is best viewed as a mathematical principle. **Interference** can be thought of as a physical realization of the superposition principle: when two waves ( $D_1$  and  $D_2$ ) meet, then

$$D = D_1 + D_2. \quad \text{fundamental for any coexisting waves}$$

**Energy in a wave:**  $E = \frac{1}{2}\rho SL\omega^2 A^2 = 2\pi^2\rho SLf^2 A^2$  (for a travelling sinusoidal wave over a length  $L$ ; medium cross section surface area  $S$ ; the SHM energy since  $\rho SL$  is the total mass).  $P = E/T$  ( $T$  is the time of travel for  $L$ ), and  $I = P/S = \frac{1}{2}\rho\omega^2 A^2 v$ . These are only for the plane wave. A point source in three dimensions will result in a spherical wave:  $I \propto r^{-2}$  since  $S = 4\pi r^2$  and  $P =$  preserved.

**Reflection, boundary condition, and phase shift:** If  $D$  is constrained to be zero (fixed end), then the wave reflects while changing sign ( $\pi$  phase shift). If  $D$  has no constraint (free end), then the reflected wave involves no sign change (no phase shift).

## Sound

**Sound wave:** Displacement wave, as well as pressure wave. Departure of the pressure from the equilibrium pressure:  $\Delta P = -B \partial D/\partial x$ . All other general properties of the wave holds for sound wave ( $v = \lambda f$ , interference, etc).

**Beats:** Arise from  $\sin(\omega_1 t + \phi_1) + \sin(\omega_2 t + \phi_2) = 2 \sin(\omega_a t + \phi_a) \cos(\omega_d t + \phi_d)$ , where  $\omega_a = (\omega_1 + \omega_2)/2$ ,  $\omega_d = (\omega_1 - \omega_2)/2$ ,  $\phi_a = (\phi_1 + \phi_2)/2$ ,  $\phi_d = (\phi_1 - \phi_2)/2$ . If  $\omega_1 \approx \omega_2$ , then this superposed wave has an “envelope” function,  $\cos(\omega_d t + \phi_d)$ , which varies slowly in time. This causes the sound *intensity* oscillate slowly in time with angular frequency =  $2|\omega_d| = |\omega_1 - \omega_2|$ . This is **the beat frequency**:  $\omega_B = |\omega_1 - \omega_2|$ , or  $f_B = |f_1 - f_2|$ .

**Decibel:** Logarithmic intensity scale (dB),  $\beta \equiv 10 \log_{10} \frac{I}{I_0}$ , where  $I_0 = 10^{-12} \text{ W/m}^2$ .

**Standing waves:** For a guitar string or an open (or closed) tube, of length  $l$ , we get  $n\lambda_n = 2l$ . For a half open tube,  $(2n-1)\lambda_n = 4l$ . Here,  $n = 1, 2, 3, \dots$ . At an open end of tube, pressure  $\Delta P$  ( $D$ ) has a node (anti-node). At a closed end of tube, displacement  $D$  ( $\Delta P$ ) has a node (anti-node). The frequencies that correspond to these discrete wave lengths,  $f_n = v/\lambda_n$ , are examples of **resonant frequencies** or **natural frequencies**, at which the object responds with singular sensitivity.

**Doppler effect:**  $f' = \frac{v \pm v_o}{v \pm v_s} f$ , where  $v_o$  ( $v_s$ ) is the speed of the observer (source) of sound, and  $v$  is the speed of sound. So,  $v, v_o, v_s$  are all positive, and the signs ( $\pm$ ) in front of  $v_o$  and  $v_s$  must be chosen based on physics. The sound medium must be at rest.